

MAIN FEATURES

ø 120 mm through hollow shaft encoder designed for medium / large size motors.

- 3 channel encoder (A / B / Z) up to 2048 ppr
- Power supply up to +28 V DC with various electrical interfaces available
- Output frequency up to 105 kHz
- Cable output, connectors available at cable end
- Through hollow shaft up to 60 mm diameter
- Shaft fixing by grub screws



ORDERING CODE

EL 120P 1024 S 5/28 P 50 X 3 PR .XXX

SERIES
incremental encoder series **EL**

MODEL
through hollow shaft with spring **120P**

RESOLUTION
ppr from **400** to **2048**
refer to the available pulses list

ZERO PULSE
without zero pulse **S**
with zero pulse **Z**

POWER SUPPLY
(with L electrical interface) 5 V DC **5**
(with L electrical interface) 8 ... 24 V DC **8/24**
5 ... 28 V DC **5/28**

ELECTRICAL INTERFACE
push-pull **P**
line driver **L**

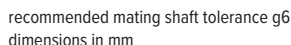
BORE DIAMETER
mm **40**
mm **50**
mm **60**

ENCLOSURE RATING
IP 54 **X**

MAX ROTATION SPEED
3000 rpm **3**

OUTPUT TYPE
radial cable (standard length 0,5 m) **PR**
preferred cable lengths 1,5 / 2 / 3 / 5 / 10 m, to be added after OUTPUT TYPE (eg. PR5)

VARIANT
custom version **XXX**



Resolution	from 400 to 2048 ppr
Power supply¹	5 = 4,5 ... 5,5 V DC 5/28 = 4,75 ... 29,4 V DC 8/24 = 7,6 ... 25,2 V DC (reverse polarity protection)
Current consumption without load	100 mA max
Max load current	C / P = 50 mA / channel L = 20 mA / channel
Electrical interface²	push-pull / line driver HTL (AEIC-7272 or similar) line driver RS-422 (AELT-5000 or similar)
Max output frequency	105 kHz
Counting direction	A leads B clockwise (shaft view)
Index signal	90°e (gated A&B)
Mean time to dangerous failure (MTTF_d)³ according to EN ISO 13849-1	429 years
Mission time (Tm)³	20 years
Diagnostic coverage (DC)³	0%
Cable type	shielded - fixed installation conductors section 0,22 mm² / AWG 24 bending radius min 60 mm
Electromagnetic compatibility	according to 2014/30/EU directive
RoHs	according to 2011/65/EU directive
UL / CSA	file n. E212495

400 - 800 - 1000 - **1024** - 1440 - 1600 - 2000 - **2048**

please directly contact our offices for other pulses, preferred resolutions in bold

for torque arm please refer to Accessories

SHAFT DIAMETER	G
ø 40	ø 65
ø 50	ø 65
ø 60	ø 75

Bore diameter	ø 40 / 50 / 60 mm
Enclosure rating	IP 54 (IEC 60529)
Max rotation speed	3000 rpm
Shock	50 G, 11 ms (IEC 60068-2-27)
Vibration	10 G, 10 ... 2000 Hz (IEC 60068-2-6)
Moment of inertia	approx 215 x 10 ⁻⁶ kgm ² (51 x 10 ⁻⁴ lbft ²)
Starting torque (at +20°C / +68°F)	< 0,05 Nm (7 Ozin)
Bearing stage material	aluminum
Shaft material	aluminum
Housing material	aluminum
Bearings	n.2 ball bearings
Bearings life	10 ⁹ revolutions
Operating temperature^{4, 5}	0° ... +60 °C (+32° ... +140°F)
Storage temperature⁵	-25° ... +70 °C (-13° ... +158°F)
Weight	750 g (26,46 oz)

¹ as measured at the transducer without cable influences

² for further details refer to OUTPUT LEVELS on TECHNICAL BASICS section

³ this product is not a safety component, for further details refer to TECHNICAL BASICS section

⁴ measured on the transducer flange⁵ condensation not allowed

Function	Cable C / P	Cable L
+V DC	red	red
0 V	black	black
A+	green	green
A-	/	brown or grey
B+	yellow	yellow
B-	/	orange
Z+	blue	blue
Z-	/	white
\perp	shield	shield