

EMSPB

LINEAR MAGNETOSTRICTIVE TRANSDUCER WITH ANALOGUE OUTPUT

MAIN CHARACTERISTICS

The EMSPB is an absolute linear magnetostrictive transducer with analogue interface.

Thanks to the absence of electrical contact on the housing, there is no problem of wear and deterioration during its working life.

Magnetostrictive technology guarantees high performance in terms of speed and accuracy. The compact size and robust housing ensure high reliability and ease of installation, even in applications with mechanical stresses, shocks or high levels of contamination.



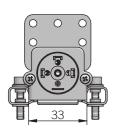


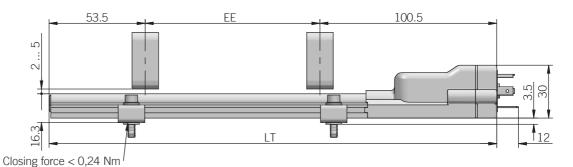


ORDERING CODE	EMSPB	1000	S	105	10	C4	Α
	SERIES linear magnetostrictive transducer with analogue output EMSPB						
		STROKE 0 to 1500					
ENCLOSURE RATING IP 65 S							
OUTPUT SIGNAL 0,1 10,1 V DC / 1 cursor (standard) 10S 4 20 mA / 1 cursor 20S							
TRAVEL SPEED max 10 m/s 10							
OUTPUT TYPE EN 175301-803 form A (DIN 43650-A) 4 pin connector C4 M12 5 pin connector S5							
OUTPUT DIRECTIC axial						ection axial A	



EMSPB





dimensions in mm

· brackets, cursors and socket connector not included, please refer to Accessories

ELECTRICAL SPECIFICATIONS				
Resolution	virtually infinite limited only by electrical noise 5 mVpp			
Output signal	0,1 10,1 V DC	4 20 mA		
Output alarm value in absense of cursor	10,5 V DC	21 mA		
Output value max	12 V DC	30 mA		
Power supply ¹	1 19,2 28,8 V DC			
Power ripple	1 Vpp max			
Current consumption	35 mA max	60 mA max		
Output load	≥ 10 kΩ	50 500 Ω		
Indipendent linearity	± 0,04 % FS max (min ± 0,09 mm)			
Repeatability	≤ 0,01 mm (typical)			
Hysteresis	≤ 0,02 mm (typical)			
Sampling time	1 ms (50 600)			
Protection against overvoltage	VAS			
Protection against polarity inversion				
Protection against power supply on output				
Electrical insulation	500 V DC			
Electromagnetic compatibility	according to JUM/RU/FU directive			
RoHS	according to 2011/65/EU directive			
The body of the bo				

¹ as measured at the transducer without cable influences

INSTALLATION NOTES

For a multi-cursor model, the cursors must operate under the same conditions of distance and temperature. The cursors must be mounted on a non-magnetic material support (such as brass, aluminium or AISI316 stainless steel).

The kit includes two screws, two nuts and two washers (all brass).

The cursor must be installed with maximum attention to horizontal alignment with the transducer axis (maximum tolerance $\pm\,2$ mm), the distance from the transducer surface must be within the range of 2 to 5 mm.

M	ECH	ANI	CAL	SP	ECI	Fl	CATI	ONS

MECHANICAL SPECIFICATIONS					
Stroke	50 - 100 - 150 - 200 - 225 - 300 - 350 - 400 - 450 - 500 - 600 - 700 - 800 - 900 - 1000 - 1100 - 1200 - 1300 - 1400 - 1500 mm				
Electric stroke (EE)	see stroke (mm)				
Overall dimension (LT)	EE + 154 mm				
Enclosure rating	IP 67 (IEC 60529)				
Detected measurement	displacement				
Travel speed	10 m/s max				
Acceleration	100 m/s² max				
Shock	100 G, 11 ms, single shot (IEC 68000-2-27)				
Vibration	12 G, 10 2000 Hz (IEC 68000-2-6)				
Housing material	anodized aluminium / Nylon 66 G 25				
Cursor type floating cursor					
Temperature coefficient	≤ 0,01 % FS / °C (min. 0,015 mm / ° C)				
Operating temperature ^{2, 3}	-20° +75°C (-4° +167°F)				
Storage temperature ³	-40° +100°C (-40° +212°F)				

CONNECTIONS					
Function	4 pin C4	M12 5 pin S5			
+V DC	3	5			
0 V	1	4			
OUTPUT	2	1			
0 V output	1	2			
NC	1	3			
÷	4	housing			

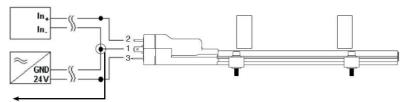
C4 connector (4 pin) EN 175301-803 form A front view



M12 connector (5 pin) M12 A coded front view



APPLICATION EXAMPLE (CURRENT OUTPUT)



Note: connect as close as possible to the transducer



^{2,3} measured on transducer

³ condensation not allowed