

MAIN FEATURES

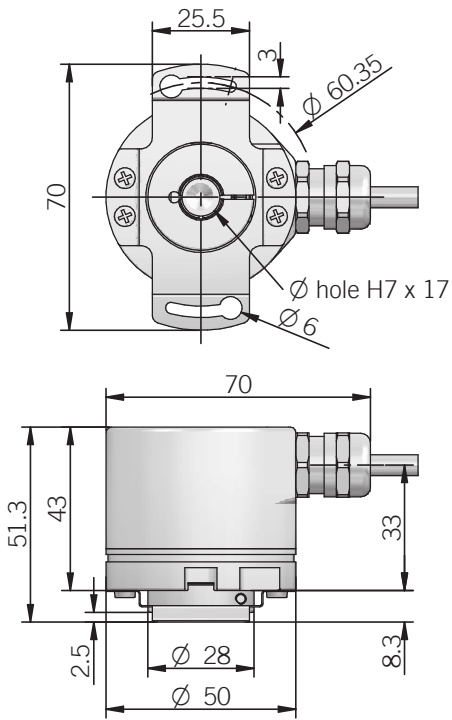
Singleturn absolute magnetic encoder size 50 mm with blind hollow shaft

- Resolution 12 bit
- Power supply up to +28 V DC with analogue (voltage or current) electrical interface
- Code reset for easy setup
- Cable or M12 output, other connectors available on cable end
- Sturdy construction
- Blind hollow shaft diameter up to 15 mm
- IP 67 enclosure rating
- Mounting by stator coupling or torque pin

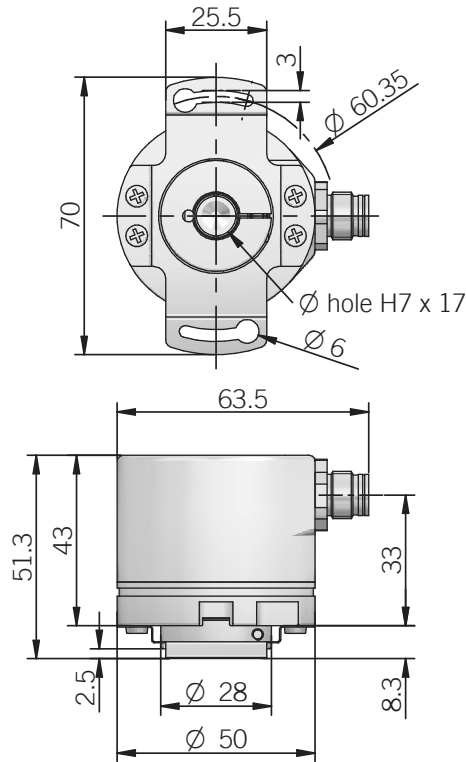


ORDERING CODE	EML	50F	360	X	12/28	V	05	X	15	X	3	M12	R	.162	+XXX
SERIES magnetic singleturn absolute encoder EML															
MODEL blind hollow shaft with stator coupling 50F blind hollow shaft with torque pin 50G															
ACTIVE ANGLE degrees 360 degrees 270 degrees 180 degrees 90															
OPTION to be reported if not used X reset with external input ZE															
POWER SUPPLY 12 ... 28 V DC 12/28															
ELECTRICAL INTERFACE voltage V current I															
OUTPUT RANGE 0 ... 5 V 05 0 ... 10 V 010 0 ... 20 mA 020 4 ... 20 mA 420															
OPTIONS to be reported with voltage output / 3 wires current output X 4 wires current output Q															
BORE DIAMETER mm 14 mm 15 diameters 5 / 6 / 8 / 10 / 12 mm with optional shaft adapter, see Accessories															
ENCLOSURE RATING IP 65 X IP 67 S															
MAX ROTATION SPEED 3000 rpm 3															
OUTPUT TYPE cable (standard length 0,5 m) P preferred cable lengths 1,5 / 2 / 3 / 5 / 10 m, to be added after DIRECTION TYPE (eg. PR5) M12 plug connector M12															
DIRECTION TYPE axial A radial R															
SOCKET socket not included .162 to be reported only with connector output (eg. M12R.162), for socket see Accessories															
VARIANT custom version XXX															

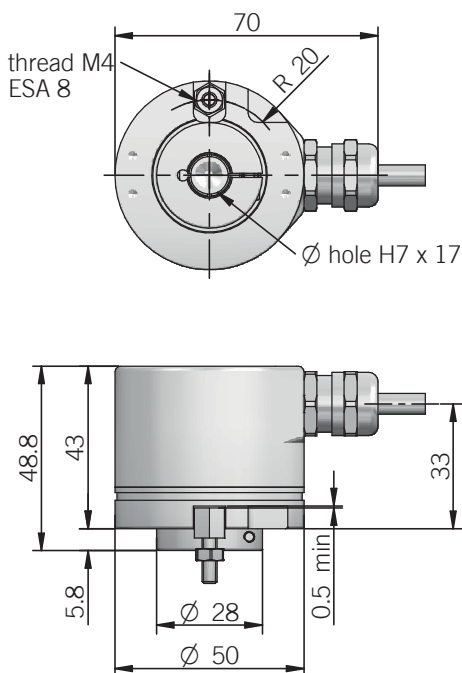
50F WITH RADIAL CABLE OUTPUT



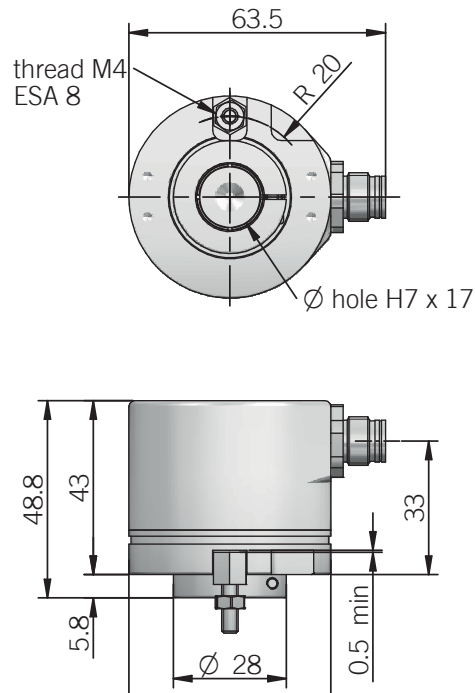
50F WITH RADIAL M12 OUTPUT



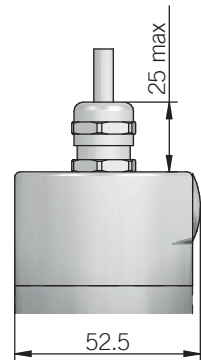
50G WITH RADIAL CABLE OUTPUT



50G WITH RADIAL M12 OUTPUT



DIMENSIONS WITH AXIAL OUTPUT



torque pin is included in model G, for mounting instruction please refer to product installation notes

recommended mating shaft tolerance g6
dimensions in mm

ELECTRICAL SPECIFICATIONS **MECHANICAL SPECIFICATIONS**

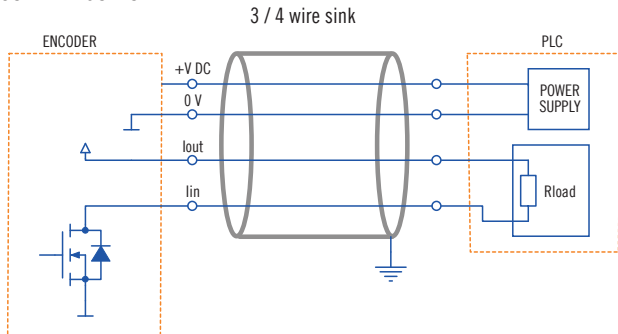
Resolution	12 bit
Output DAC resolution	12 bit
Active angle	90 ... 360 mechanical degrees
Power supply¹	11,4 ... 29,4 V DC (reverse polarity protection)
Current consumption without load	40 mA max
Electrical interface²	voltage (0 ... 5 V / 0 ... 10 V) current (0 ... 20 mA / 4 ... 20 mA)
Auxiliary inputs (U/D - RESET)	active high (+V DC) connect to 0 V if not used / RESET tmin 150 ms
Load	$R_{min} = 1 \text{ k}\Omega$ (voltage output) $R_{max} = (V_{DC} - 2) / 0,02$ (current output)
Output update frequency	100 kHz
Signal pattern	decreasing clockwise (shaft view)
Start-up time	150 ms
Linearity error	< 1 %
Mean time to dangerous failure (MTTF)³ according to EN ISO 13849-1	153 years
Mission time (Tm)³	20 years
Diagnostic coverage (DC)³	0%
Cable type	shielded - fixed installation conductors section 0,22 mm ² / AWG 24 bending radius min 60 mm
Electromagnetic compatibility	according to 2014/30/EU directive
RoHS	according to 2011/65/EU directive
UL / CSA	file n. E212495

Bore diameter	ϕ 14 / 15 mm ϕ 5 / 6* / 8* / 10* / 12* mm * with optional shaft adapter, please refer to Accessories
Enclosure rating IEC 60529	X = IP 65 S = IP 67
Max rotation speed	3000 rpm continuous
Max shaft load⁴	30 N (6,74 lbs) axial / 50 N (11,24 lbs) radial
Shock	50 G, 11 ms (IEC 60068-2-27)
Vibration	20 G, 10 ... 2000 Hz (IEC 60068-2-6)
Moment of inertia	$4 \times 10^{-6} \text{ kgm}^2$ ($95 \times 10^{-6} \text{ lbft}^2$)
Starting torque (at +20°C / +68°F)	< 0,03 Nm (4,25 Ozin)
Bearing stage material	aluminum
Shaft material	stainless steel
Housing material	painted aluminum
Bearings	n.2 ball bearings
Bearings life	10^9 revolutions
Operating temperature^{5,6}	-25° ... +85°C (-13° ... +185°F)
Storage temperature⁶	-25° ... +85°C (-13° ... +185°F)
Weight	200 g (7,05 oz)

¹ as measured at the transducer without cable influences
² for further details refer to OUTPUT LEVELS on TECHNICAL BASICS section
³ this product is not a safety component, for further details refer to TECHNICAL BASICS section
⁴ maximum load for static usage
⁵ measured on the transducer flange
⁶ condensation not allowed

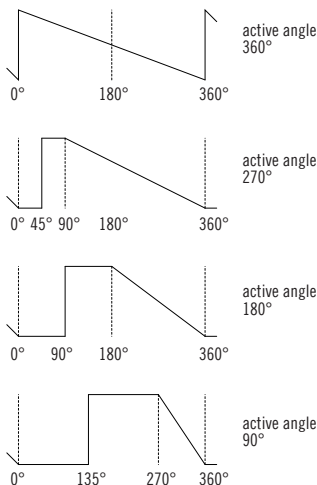
ELECTRICAL INTERFACE

CURRENT OUTPUT

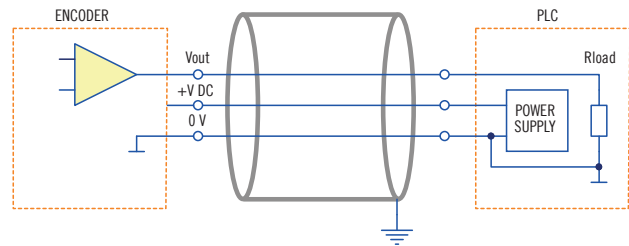


with 3 wires interface I_{out} is internally connected to +V DC
 where $R_{LOAD} \text{ max} = (V_{DC} - 2) / 0,02$

SIGNAL PATTERN (decreasing CW)



VOLTAGE OUTPUT



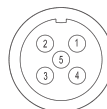
where $R_{LOAD} \text{ min} = 1 \text{ k}\Omega$

CONNECTIONS

Function	Cable (voltage)	Cable (current)	5 pin M12	8 pin M12*
+ V DC	red	red	2	8
0 V	black	black	4	5
V _{out}	green	/	3	/
I _{in}	/	yellow	3	3
I _{out}	/	green	/	2
U / D	blue	blue	5	7
RESET	white	white	1	1
⊥	shield	shield	housing	housing

* with Q current output

M12 connector (5 pin)
M12 A coded
front view



M12 connector (8 pin)
M12 A coded
front view

